

Single Impulse De-orbit from Circular and Elliptical Orbits

This document summarizes equations that can be used to determine the characteristics of single impulse, coplanar two-body de-orbit trajectories from circular and elliptical orbits. For both types of initial orbits, the de-orbit maneuver consists of a tangential impulsive ΔV applied opposite to the velocity vector of the initial orbit at the maneuver orbital location. For de-orbit from elliptical orbits, the maneuver is performed at apogee. The user-defined mission constraints at the entry interface (EI) are altitude and flight path angle relative to a spherical Earth.

De-orbit from a circular orbit

The scalar magnitude of the single impulsive maneuver required to de-orbit a spacecraft from an initial circular orbit can be determined from the following expression

$$\Delta V = V_{c_e} \sqrt{\frac{1}{\tilde{r}}} \left\{ 1 - \frac{\sqrt{\frac{2(\tilde{r}-1)}{\left(\frac{\tilde{r}}{\cos \gamma_e}\right)^2 - 1}}}{\sqrt{\left(\frac{\tilde{r}}{\cos \gamma_e}\right)^2 - 1}} \right\} = V_{c_i} \left\{ 1 - \frac{\sqrt{\frac{2(\tilde{r}-1)}{\left(\frac{\tilde{r}}{\cos \gamma_e}\right)^2 - 1}}}{\sqrt{\left(\frac{\tilde{r}}{\cos \gamma_e}\right)^2 - 1}} \right\}$$

where

$$\tilde{r} = \frac{h_i + r_{eq}}{h_e + r_{eq}} = \frac{r_i}{r_e} = \text{radius ratio}$$

$$V_{c_e} = \sqrt{\frac{\mu}{(h_e + r_{eq})}} = \sqrt{\frac{\mu}{r_e}} = \text{local circular velocity at entry interface}$$

$$V_{c_i} = \sqrt{\frac{\mu}{(h_i + r_{eq})}} = \sqrt{\frac{\mu}{r_i}} = \text{local circular velocity of initial circular orbit}$$

γ_e = flight path angle at entry interface

h_i = altitude of initial circular orbit

h_e = altitude at entry interface

r_i = radius of initial circular orbit

r_e = radius at entry interface

r_{eq} = Earth equatorial radius

μ = Earth gravitational constant

This algorithm is described in the technical article, “Deboost from Circular Orbits”, A. H. Milstead, *The Journal of the Astronautical Sciences*, Vol. XIII, No. 4, pp. 170-171, Jul-Aug., 1966. Additional information can be found in Chapter 5 of *Hypersonic and Planetary Entry Flight Mechanics* by Vinh, Busemann and Culp, The University of Michigan Press.

The true anomaly on the de-orbit trajectory at the entry interface θ_e can be determined from the following two equations:

$$\sin \theta_e = \frac{\dot{r}}{e_d} \sqrt{\frac{a_d(1-e_d^2)}{\mu}}$$

$$\cos \theta_e = \frac{a_d(1-e_d^2)}{e_d r_e} - \frac{1}{e_d}$$

and the following four quadrant inverse tangent operation

$$\theta_e = \tan^{-1}(\sin \theta_e, \cos \theta_e)$$

where

e_d = eccentricity of the de-orbit trajectory

a_d = semimajor axis of the de-orbit trajectory

$$\dot{r} = -\sqrt{\frac{\mu [2a_d r_e - r_e^2 - a_d^2 (1-e_d^2)]}{a_d r_e^2}}$$

The elapsed time-of-flight between perigee of the de-orbit trajectory and the entry true anomaly θ_e is given by

$$t(\theta_e) = \frac{\tau}{2\pi} \left[2 \tan^{-1} \left\{ \frac{\sqrt{1-e_d}}{\sqrt{1+e_d}} \tan \frac{\theta_e}{2} \right\} - \frac{e_d \sqrt{1-e_d^2} \sin \theta_e}{1+e_d \cos \theta_e} \right]$$

In this equation τ is the Keplerian orbital period of the de-orbit trajectory and is equal to $2\pi \sqrt{a_d^3/\mu}$.

Therefore, the flight time between the de-orbit impulse and entry interface is given by

$$\Delta t = t(\theta_e) - t(180^\circ) = t(\theta_e) - \frac{\tau}{2}$$

Finally, the orbital speed at the entry interface V_e can be determined from

$$V_e = \sqrt{\frac{2\mu}{r_e} - \frac{\mu}{a_d}}$$

Here's a numerical example that uses these equations. For this example, the entry altitude is 121.92 kilometers and entry flight path angle is -2 degrees. The impulsive maneuver creates an elliptical orbit with an apogee altitude equal to the altitude of the initial circular orbit.

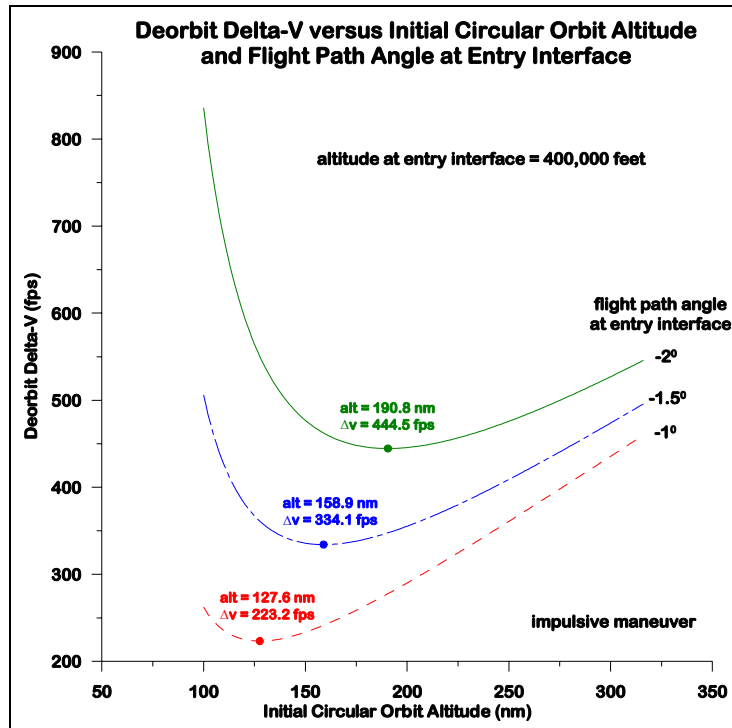
initial orbit

altitude	400.000000	kilometers
entry altitude	121.920000	kilometers
entry fpa	-2.000000	degrees

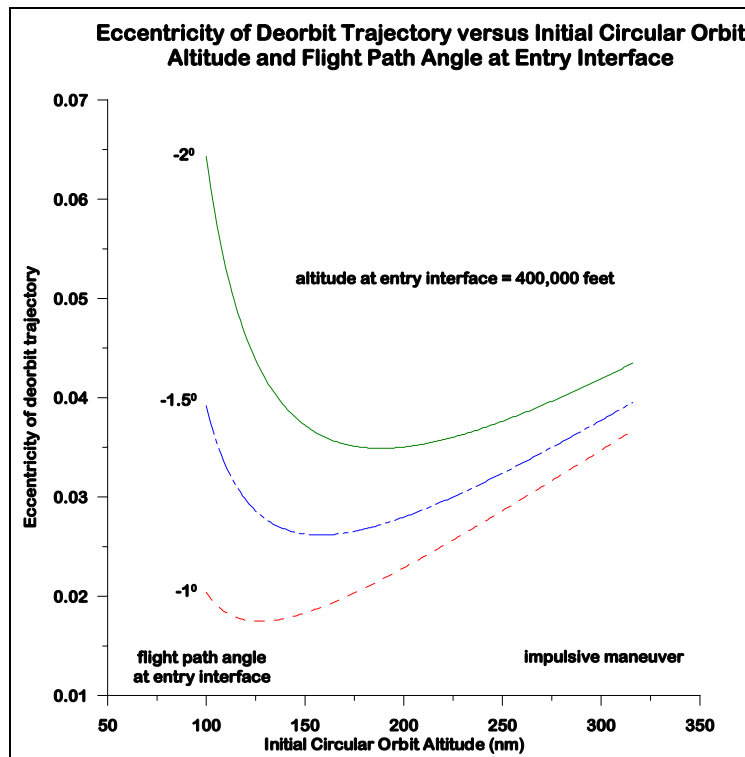
entry trajectory

semimajor axis	6545.28443641	kilometers
eccentricity	0.03557608	
argument of perigee	180.00000000	degrees
perigee altitude	-65.71112719	kilometers
apogee altitude	400.00000000	kilometers
entry true anomaly	279.19205809	degrees
entry velocity	7857.88102977	meters/second
impulse-to-entry time	25.17812758	minutes
deorbit delta-v	137.64389361	meters/second

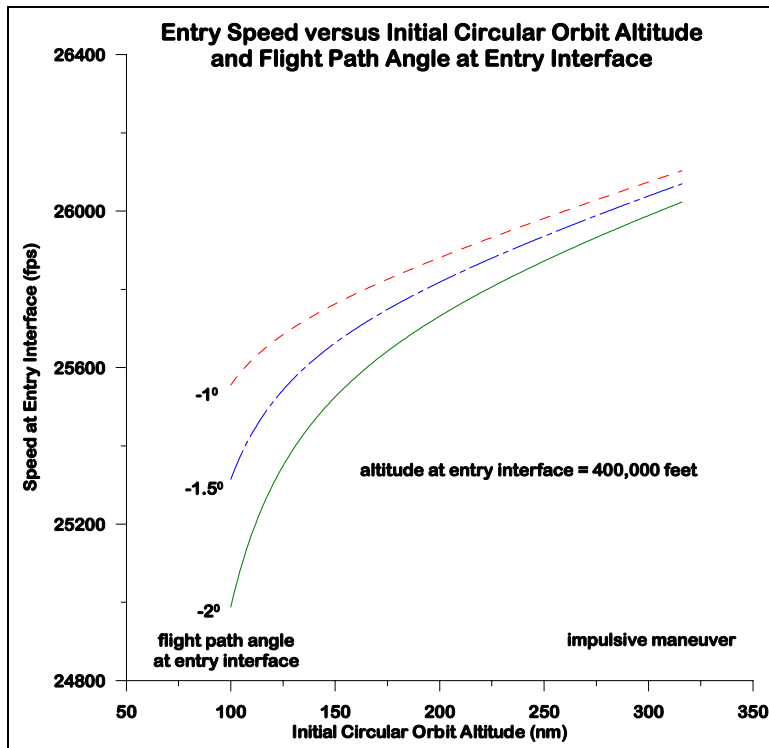
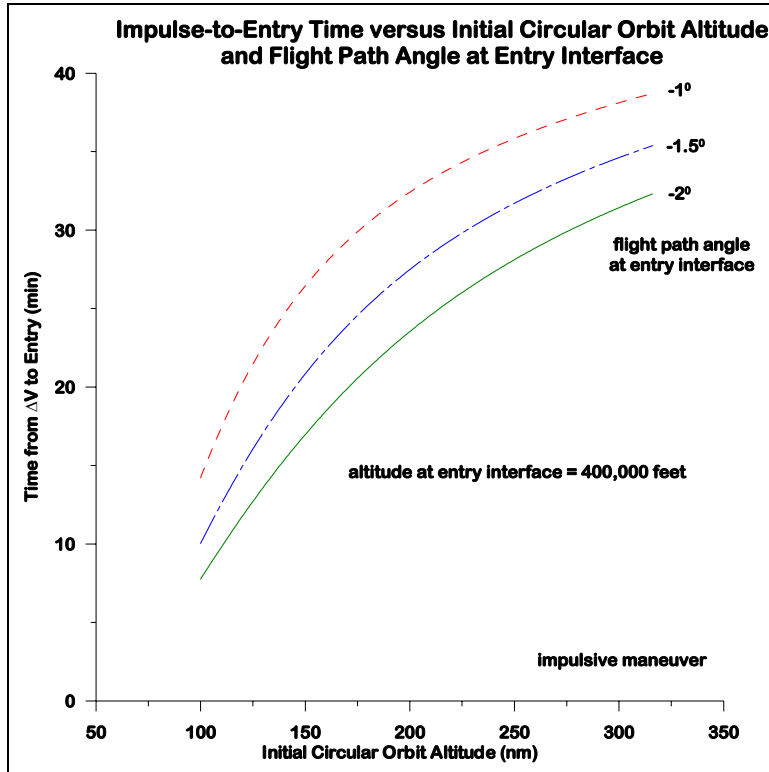
The following is a graphic display of the single impulsive ΔV required to de-orbit from a range of circular Earth orbit altitudes and several entry interface flight path angles. The entry interface altitude for this example is 400,000 feet.



This plot is also labeled with the minimum de-orbit altitude and corresponding ΔV for a given flight path angle at the entry interface. An examination of the following plot of the eccentricity of the de-orbit trajectory reveals why these minima exist.



The next two plots illustrate the behavior of the impulse-to-entry mission time and speed at the entry interface.



De-orbit from an elliptical orbit

The scalar magnitude of the impulsive delta-v for de-orbit from an initial elliptical orbit is given by

$$\Delta V = \sqrt{\frac{\mu}{r_e}} \left(\sqrt{\frac{2\tilde{r}_p}{\tilde{r}_a(\tilde{r}_a + \tilde{r}_p)}} - \sqrt{\frac{2(\tilde{r}_a - 1)}{\tilde{r}_a(\tilde{r}_a^2 - \cos^2 \gamma_e)}} \cos \gamma_e \right)$$

where

r_e = geocentric radius at the entry altitude

$\tilde{r}_a = r_a / r_e$

$\tilde{r}_p = r_p / r_e$

γ_e = flight path angle at entry

r_a = apogee radius of the initial elliptical orbit

r_p = perigee radius of the initial elliptical orbit

μ = gravitational constant of the Earth

The true anomaly at entry can be determined from the following series of equations.

$$\sin \theta_e = \frac{\dot{r}}{e_d} \sqrt{\frac{a_d(1 - e_d^2)}{\mu}}$$

$$\cos \theta_e = \frac{a_d(1 - e_d^2)}{e_d r_e} - \frac{1}{e_d}$$

$$\theta_e = \tan^{-1}(\sin \theta_e, \cos \theta_e)$$

where

e_d = eccentricity of the de-orbit trajectory

a_d = semimajor axis of the de-orbit trajectory

$$\dot{r} = -\sqrt{\frac{\mu [2a_d r_e - r_e^2 - a_d^2(1 - e_d^2)]}{a_d r_e^2}}$$

The time-of-flight between perigee and the entry true anomaly θ_e is given by

$$t(\theta_e) = \frac{\tau}{2\pi} \left[2 \tan^{-1} \left\{ \sqrt{\frac{1-e_d}{1+e_d}} \tan \frac{\theta_e}{2} \right\} - \frac{e_d \sqrt{1-e_d^2} \sin \theta_e}{1+e_d \cos \theta_e} \right]$$

In this equation τ is the orbital period of the de-orbit trajectory.

Therefore, the flight time between the de-orbit impulse time and entry is given by

$$\Delta t = t(\theta_e) - t(180^\circ) = t(\theta_e) - \frac{\tau}{2}$$

Finally, the speed at reentry V_e can be determined from

$$V_e = \sqrt{\frac{2\mu}{r_e} - \frac{\mu}{a_d}}$$

Here's a numerical example that uses these equations. For this example, the entry altitude is 111.252 kilometers and entry flight path angle is -4 degrees.

initial orbit

perigee altitude	285.798000	kilometers
apogee altitude	35785.922000	kilometers
semimajor axis	24414.000000	kilometers
eccentricity	0.727044	
entry altitude	111.252000	kilometers
entry fpa	-4.000000	degrees

de-orbit trajectory

semimajor axis	24308.08290588	kilometers
eccentricity	0.73456961	
perigee altitude	73.96381175	kilometers
apogee altitude	35785.92200000	kilometers
entry true anomaly	350.55084585	degrees
entry velocity	10317.40933180	meters/second

entry fpa	-4.00000000	degrees
impulse-to-entry time	312.58844372	minutes
de-orbit delta-v	22.29796787	meters/second